

Voltage stability analysis based on multi-objective optimal reactive power dispatch under various contingency

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Abstract: An effective allocation of the reactive power in an electrical network aims generally to improve the voltage profile and to control transmission power losses. The present paper proposes the application of an efficient hybrid method combining two evolutionary search techniques. The technique is based on Particle Swarm Optimization (PSO) algorithm and Gravitational Search Algorithm (GSA) to solve the Optimal Reactive Power Planning (ORPP) problem for energy losses cost minimization of Algerian electric power system using the static Var Compensator devices (SVC). To ensure viability of the power system in contingency cases, various critical situations are simulated in order to prevent and prepare the power system to face such situations. The proposed program handles most changes that can occur in to the power system (heavy load, losing a large generator, losing a critical line ...etc.). The proposed method is applied to solve the ORPP problem on the equivalent Algerian electric power system 114-bus. Moreover, the obtained results are compared, with PSO and GSA, separately. The results obtained by the proposed method show it's effectiveness for improving the reactive power planning problem.

Index Terms: Optimal reactive power planning, Hybrid PSO-GSA, Stability Index, Equivalent Algerian electric power system.

1. Introduction

Through adjusting voltage generator, reactive power generator, transformer taps, and reactive power sources (capacitive or inductive banks, FACTS devices, etc.), the reactive power planning can reduce voltage deviations and active power losses. And in the same time maximizing voltage stability margin [1-2]. Since the generator reactive power, generator voltages, the transformer ratios and reactive power sources are continuous, the optimization problem is a nonconvex nonlinear programming problem (NLP). To solve such problem many conventional methods [3-5], like stochastic search methods [5-11] and hybrid conventional-stochastic methods [1], have been proposed.

To insure the power system security, the OPRPP problem is associated with the contingency analysis problem. The contingency analysis, which is a well-known function in power system planning and operation [11-15], is used later to predict the contingencies which make system violated and rank the contingencies according to their relative severity. An outage of a transmission line, capacitor bank or transformer may lead to over loads in other branches and sudden system voltage rise or drop. This may lead to complete blackout. In this paper, three critical contingency cases are studied, these are: 1) Heavy load, 2) Lose a large Generator, 3) Lose a critical line. These cases are studied in a way to guarantee: i) The system stability after the increase of the power system load (voltage level, active and reactive power and load tap changer value are in the secure range), ii) The stability system maintainability after the outage of a large generator and a critical line, iii) a better location choice of the SVC's devices is for improving the network voltage level and stability.

In this paper, the voltage instability analysis study, which is one of the critical issues in electric power system [16-17], is also considered in a way to identify the critical buses to locate the SVC's devices and the critical lines for the contingency study purpose. For this purpose, three different stability indexes namely Fast Voltage Stability Index (FVSI)[18], Line stability index (Lmn 19) and Line Stability Factor(LPQ) [20] are used.

To solve the ORPP problem, which is a nonlinear optimization problem, we have opted to use a hybrid meta-heuristic technique combining a particle swarm optimization method and the gravitational search algorithm (PSO-GSA) [21]. In the first part of this method, the PSO is used. This method is a stochastic search technique developed by Kennedy and Eberhart [22] and has been found to be robust and flexible in solving optimization problem, because it can generate a high quality solution within shorter calculation time and more stable convergence characteristic than other stochastic methods. In the second part, the GSA method is used [23]. It is a novel optimization method based on the law of gravity and mass interactions. It has good ability to search for the global optimum. However, these methods suffer from its low computational speed. Hence, the use of the hybridization PSO & GSA aims to give to the new algorithm more effective and efficient. Also, it can find the optimal solution with less computational time with more accuracy. The principle of the hybrid technique used in this paper is base on the exploitation of the feature of the GSA in the initial stages of the search process, and the exploring feature of the PSO during the later stages of the algorithm [21]. In [21], IrajKheirizad have used use twenty-three benchmark functions to validate the performance of the PSO GSA algorithm and was compared to standard PSO and GSA. The obtained results show that the number of functions performed well by the PSO GSA is nearly twice of functions performed by PSO and GSA. This comparison shows the robustness and the effectiveness of the PSO and GSA. The results also have shown that the convergence speed of PSO GSA is faster with stable convergence characteristic than other stochastic methods [21]. A state of the art of the use of the proposed method in several electrical engineering domains is presented in the appendix section.

The proposed approach has been applied to the ORPP problems using SVC's device for the equivalent Algerian electric power system 114-bus. Three stability index methods, *FVSI*, *Lmn*, and *LPQ* are used to identify the weakest buses and lines where to install the SVC's devices.

Appendix A

This section contains a state of art of the hybrid PSO GSA technique surfaced in the recent state-of-the-art literature:

Table A1. A state of art of the hybrid PSO GSA technique.

Reference		Paper Title	Year
[25]	-Optimal location and optimal size of the SVC.	1-A Novel Algorithm for Optimal Location of FACTS Devices in Power System Planning.	2008
[30]		2-Optimal Location and Sizing of Multiple Static VAR Compensators for Voltage Risk Assessment Using Hybrid PSO-GSA Algorithm.	2014
[26]	-Optimal tuning of Takagi- Sugeno-Kang PI-fuzzy controllers (T-S-K PI-FCs).	-Adaptive Hybrid Particle Swarm Optimization- Gravitational Search Algorithm for Fuzzy Controller Tuning.	2014
[27]	-Static State Estimation (SE) problem.	-Optimal static state estimation using improved particle swarm optimization and gravitational search algorithm.	2013

[28]	-Optimal reactive power dispatch (ORPD) problem for real power loss and the bus voltage deviations minimization.	-A New Hybrid PSOGSA Algorithm for Solving Optimal Reactive Power Dispatch Problem.	2014
[29]	-Optimal path planning algorithm for mobile robots.	-Hybrid PSO-GSA Robot Path Planning Algorithm in Static Environments with Danger Zones.	2013
[31]	-Economic Load Dispatch Problem (ELD) problem.	-Application of New Hybrid Particle Swarm Optimization and Gravitational Search Algorithm for Non Convex Economic Load Dispatch Problem.	2013
[32]		-A Novel Hybrid PSO-GSA Method for Non-convex Economic Dispatch Problems.	2013
[33]	-Economic emission load dispatch (EELD) problems	-A novel hybrid particle swarm optimization and gravitational search algorithm for solving economic emission load dispatch problems with various practical constraints	2014

2. Problem Formulation

In this paper, the global objective function of the ORPP problem aims to minimize two objective functions which are: 1) Minimization the Compensation devices amount, 2) minimization of Cost of energy losses, while satisfying several equality and inequality constraints.

The proposed formulation of the ORPP problem is expressed as follows:

$$\min_{u,x} f_{VAR}(U, X) / \min_{u,x} f_{Wc}(U, X)$$

$$\text{Subject to } \begin{cases} G(U, X) = 0 \\ H(U, X) \leq 0 \\ U_{min} \leq U \leq U_{max} \\ X_{min} \leq X \leq X_{max} \end{cases} \quad (1)$$

with:

$$U = [V_G, T_R, Q_C] \& \quad X = [V_L, P_G, Q_G] \quad (2)$$

A. Problem objectives

A.1. Compensation devices investment cost minimization

The total investment cost function of the compensation devices is composed by the fixed installation cost and the purchase cost.

This function is considered as a linear function [24]:

$$f_{VAR}(X,U) = \sum_{i=0}^{N_{var}} \left(C_{fi} + C_{ci} |Q_{ci}| \right) \quad (3)$$

A.2. Cost of energy losses minimization function

The objective function of the cost of energy losses is represented as [24]:

$$f_{Wc} = h \sum_{i \in N_{Li}} d_i \left[G_k(i, j)(V_i^2 + V_j^2 + 2V_i V_j \cos(\theta_i - \theta_j)) \right] \quad (4)$$

Where d is the duration of load level I (see Table1).

A.3. Proposed objective Function

The proposed objective function is as follow [24]:

$$f_{cost} = f_{Wc} + f_{VAR} \quad (5)$$

B. System constraints

B.1. Equality constraints

Equality constraints represent typical load flow equations as follows:

$$P_{Gj} - P_{Di} - V_i \sum_{j=1}^{NB} V_j (G_{ij} \cos \theta_{ij} + B_{ij} \sin \theta_{ij}) = 0 \quad i = 1, 2, \dots, N_{bus} \quad (6)$$

$$Q_{Gj} - Q_{Di} - V_i \sum_{j=1}^{NB} V_j (G_{ij} \sin \theta_{ij} - B_{ij} \cos \theta_{ij}) = 0 \quad j = 1, 2, \dots, N_{bus} \quad (7)$$

B.2. Inequality constraints

The inequality constraints represent the system operating constraints.

Generator constraints: The generator voltages V_G and reactive power outputs Q_G are restricted by their upper and lower limits as follows:

$$V_{Gi}^{min} \leq V_{Gi} \leq V_{Gi}^{max} \quad i = 1, 2, \dots, N_G \quad (8)$$

$$Q_{Gi}^{min} \leq Q_{Gi} \leq Q_{Gi}^{max} \quad i = 1, 2, \dots, N_G \quad (9)$$

Switchable VAR constraints: Switchable VAR compensations are restricted by their lower and upper limits as follows:

$$Q_{Ci}^{min} \leq Q_{Ci} \leq Q_{Ci}^{max} \quad i = 1, 2, \dots, N_c \quad (10)$$

Transformer constraints: transformer tap settings are bounded as follow:

$$T_i^{min} \leq T_i \leq T_i^{max} \quad i = 1, 2, \dots, N_T \quad (11)$$

4-Security constraints: these constraints include the constraints of voltage at load V_L bus and transmission line loading $\{S_t^{from}, S_t^{to}\}$ as follows:

$$V_{Li}^{min} \leq V_{Li} \leq V_{Li}^{max} \quad i = 1, 2, \dots, N_{Load} \quad (12)$$

$$\{S_t^{from}, S_t^{to}\} \leq S_{max}^i \quad i = 1, 2, \dots, N_{Li} \quad (13)$$

3. Identification of critical buses and lines

The Stability indices have been usually used in power system for the purpose of voltage stability valuation. They can be an indicator to assess the state of a power system, whether it is healthy or stressed. The purpose of voltage stability index is to determine the point of voltage instability, the weakest bus in the system and the critical line. In this paper, a new voltage stability

index is proposed to evaluate the line stability condition in a power system and to identify the system critical buses and lines.

The proposed stability indexes are as follows:

A. Fast Voltage Stability Index (FVSI)

The Fast Voltage Stability Index FVSI is proposed by I. Musirin et al [18]. It is formulated on the base of a power transmission concept in a single line.

The mathematical formulation of the FVSI is so simple that it can be calculated on-line. Taking the symbols i as the sending bus and j as the receiving bus. Hence, the fast voltage stability index (FVSI) can be represented as:

$$FVSI = \frac{4Z^2 Q_j X}{V_i^2 X} \quad (14)$$

B. Line Stability Index (Lmn)

The line stability index Lmn proposed by Moghavvemi et al. [19] is formulated on the base of a power transmission concept in a single line.

The line stability index can be reproduced as:

$$Lmn_{ij} = \frac{4Q_r X}{[|V_i| \sin(\Theta - \delta)]^2} \quad (15)$$

C. Line Stability Factor (LPQ).

The LQP was proposed by A. Mohamed et al [20]. It was used in the comparison since this factor is more sensitive to a reactive power change. LQP is calculated as:

$$LPQ = 4 \left(\frac{X}{V_i^2} \right) \left(\frac{X}{V_i^2} P_i^2 + Q_j \right) \quad (16)$$

The value of voltage stability index must to be kept between 0 and 1. If it is close to 1, it means that it is near to the instability point. Consequently, the voltage instability could occur. And if it is close to 0, it means that the system is very secure.

The steps implemented for identifying the critical buses and lines are taken from [7].

4. Proposed method Hybrid PSO-GSA technique

The hybrid algorithm proposed in this study is a combination of PSO algorithm and GS algorithm. The PSOGSA is a new hybrid method which has been proposed by S.Mirjalili et al. in 2010 [21]. The basic idea of PSOGSA is to combine the ability of social thinking ($gbest$) in PSO [22] with the local search capability of GSA [23]. To combine these algorithms; the following formulation is used [22]:

$$V_i(t+1) = w \times V_i(t) + c_1 \times rand \times ac_i(t) + c_2 \times rand \times (gbest + X_i(t)) \quad (17)$$

The positions of particles are updated at each iteration as follow [21]:

$$X_i(t+1) = X_i(t) + V_i(t+1) \quad (18)$$

The flowchart of PSO-GSA is shown in Figure 1.

The details of the PSO-GSA based optimization algorithm are as follows:

- Step 1: A set of initial populations are created randomly within the minimum and maximum limits of the control variables. This initial populations is chosen as a parent populations
- Step 2: The objective function for each agent in the initial population is evaluated.
- Step 3: Calculate Gravitational force, gravitational constant and resultant forces among agents using (19), (20), and (21) respectively:

$$\rightarrow F_{ij}^d(t) = G(t) \frac{M_{pi}(t) \times M_{aj}(t)}{R_{ij}(t) + \varepsilon} (x_j^d(t) - x_i^d(t)) \quad (19)$$

$$\rightarrow G(t) = G_0 \times \exp(-\alpha \times \text{iter} / \text{max iter}) \quad (20)$$

$$\rightarrow F_i^d(t) = \sum_{\substack{j=1 \\ j \neq i}}^N \text{rand}_j F_{ij}^d(t) \quad (21)$$

Step 4: Calculate M acceleration for all agents of particles as defined in (22).

$$ac_i^d(t) = \frac{F_i^d(t)}{M_{ii}(t)} \quad (22)$$

Step 5: Calculate velocities of all agents using (17).

Step 6: Update position of each agent according to (18).

Step 7: The objective function for the new searching points and the evaluation values are calculated. The process of updating velocities and positions will be stopped when the end criterion it met.

Step 8: If the stopping criterion is met (which means that the maximum number of generation is reached or the optimal point is achieved), the results is printed. Otherwise, go to Step 2.

Step 9: Return the best solution.

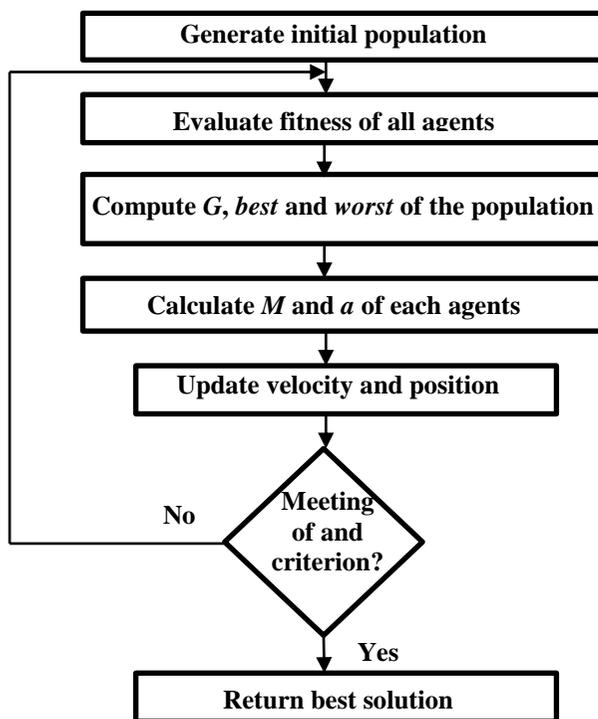


Figure 1. Flow Chart of the PSO-GSA algorithm.

A. PSOGSA for ORPP problem

In the ORPP problem, the elements of the solution consist of all control variables, namely, generator bus voltages (V), the transformer tap-setting (T) and the reactive power generation (Q_c). The proposed objective function can minimize three objective functions by satisfying the constraints given by equations (8) to (13). For each individual, the dependent variables presented

in (9, 12 and 13) and the equality constraints given by equations (6) and (7) are satisfied by running the power flow Newton-Raphson algorithm. The control variables presented in (8, 10 and 11) are self-controlled. And the dependent variables are added in the quadratic penalty terms to the objective function in order to keep their final value close to their operating limits.

$$F = f_{\cos t} + \sigma_{V_i} \sum_{i \in N_{PQ}} (V_i - V_i^{lim})^2 + \sigma_{Q_{Gi}} \sum_{i \in N_G} (Q_{Gi} - Q_{Gi}^{lim})^2 + \sigma_{S_i^t} \sum_{i \in N_{2Li}} (S_i^t - S_i^{lim})^2 \quad (23)$$

In the above objective function V_i^{lim} , Q_{Gi}^{lim} and S_i^{lim} are defined in the following equations.

$$\begin{aligned} V_i^{lim} &= \begin{cases} V_i^{min}, & \text{if } V_i < V_i^{min} \\ V_i^{max}, & \text{if } V_i > V_i^{max} \\ V_i, & \text{if } V_i^{min} < V_i < V_i^{max} \end{cases} & Q_{Gi}^{lim} &= \begin{cases} Q_{Gi}^{min}, & \text{if } Q_{Gi} < Q_{Gi}^{min} \\ Q_{Gi}^{max}, & \text{if } Q_{Gi} > Q_{Gi}^{max} \\ Q_{Gi}, & \text{if } Q_{Gi}^{min} < Q_{Gi} < Q_{Gi}^{max} \end{cases} \\ S_i^{lim} &= \begin{cases} S_i^{min}, & \text{if } S_i^t < S_i^{min} \\ S_i^{max}, & \text{if } S_i^t > P_{G1}^{max} \\ S_i^t, & \text{if } S_i^{min} < S_i^t < S_i^{max} \end{cases} \end{aligned} \quad (24)$$

5. SVC Model

The SVC is defined as a shunt connected static Var generator or consumer, whose output is adjusted to exchange capacitive or inductive current in order to control specific parameters of the power system, typically bus voltage. In this paper, the SVC is modeled as a variable shunt reactive susceptance jb_{svc} installed at the node i . In this case, only one term of the nodal admittances, corresponding to the node where the SVC is connected (see Figure 2) [1], matrix is modified.

The difference between the line susceptance before and after the addition of SVC can be expressed as:

The admittance matrix Y_{bus} before the addition of SVC:

$$\underline{Y}_{bus} = \begin{bmatrix} \underline{y}_{ij} + \frac{\underline{y}_{ij0}}{2} & -\underline{y}_{ij} \\ -\underline{y}_{ij} & \underline{y}_{ij} + \frac{\underline{y}_{ij0}}{2} \end{bmatrix} \quad (25)$$

The new system admittance matrix Y'_{bus} can be updated as:

$$\underline{Y}'_{bus} = \begin{bmatrix} \underline{y}_{ij} + \frac{\underline{y}_{ij0}}{2} + \underline{y}_{svc} & -\underline{y}_{ij} \\ -\underline{y}_{ij} & \underline{y}_{ij} + \frac{\underline{y}_{ij0}}{2} \end{bmatrix} \quad (26)$$

where

$$\underline{y}_{svc} = jb_{svc} \quad (27)$$

$$\underline{y}_{ij} = G_{ij} + jB_{ij} \quad \text{and} \quad G_{ij} = \frac{R_{ij}^{line}}{(R_{ij}^{line})^2 + (X_{ij}^{line})^2}, B_{ij} = -\frac{X_{ij}^{line}}{(R_{ij}^{line})^2 + (X_{ij}^{line})^2} \quad (28)$$

Because Y'_{bus} has to be updated for different size of SVC (b_{SVC}), the above formulation is applied at each iteration [1].

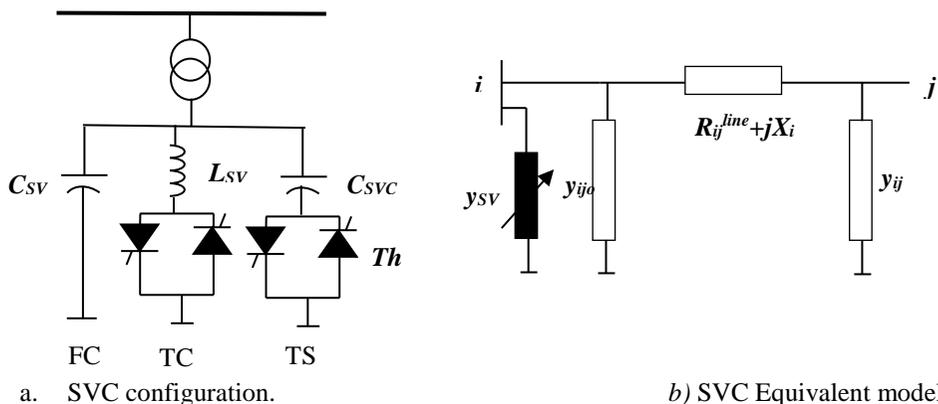


Figure 2. Static VAR compensator (SVC).

6. Simulation Results

In order to verify the effectiveness of the proposed approach, the hybrid particle swarm optimization and gravitational search algorithm (PSOSGA) has been tested on the equivalent Algerian electric power system 114-bus (220/60 kV). For comparison purpose, two other algorithms are also implemented for solving the problem, namely Particle Swarm Optimization (PSO) and Gravitational Search Algorithm (GSA). Table 2 shows the parameters, number of iterations and population size of these algorithms. The penalty factors in (25) are listed in Table 3. The programs have been written in MATLAB-7 language and executed on a 2.91 GHz CPU dual-core with 4 GO RAM.

Table 1. Duration of load level.

Cases	Case1	Case2	Case3	Sace4	Case5
d_i (hour)	8760	8760	4380	8760	8760

Table 2. Minimization parameter setting.

Parameters	PSO-GSA	PSO
C1	1.5	0.9
C2	0.5	1.1
W	[0,1]	
G0	100	
α	10	
Generation and Population size		150
No. of generation		50
Population size		

Table 3. Optimal penalty factor.

λ	λ_{v_i}	$\lambda_{Q_{Gi}}$	λ_s
IEEE 30-bus	100	50	100
Algerian 114- bus	500	100	100

To validate the effectiveness of proposed approach; five different study cases are considered (see Table 4):

Table 4. Study cases.

Cases	Algerian 114-bus
Cases 1	Base case (nominal point).
Cases 2	Uniform load variation of 20 per cent from base case.
Cases 3	1- Base case 2-Uniform load variation of 15 per cent from base case.
Cases 4	Uniform load variation of 15 per cent from base case+ suppression of Generator 11.
Cases 5	Uniform load variation of 15 per cent from base case+ suppression of line 17-27.

The real power saving P_{save} and the annual cost saving W_c^{save} is calculated to compare the performance of the proposed algorithm with PSO and GSA methods.

$$\text{with } P_{save} \% = \frac{P_{loss}^{init} - P_{loss}^{opt}}{P_{loss}^{init}} \text{ And } W_c^{save} = hd_i (P_{loss}^{init} - P_{loss}^{opt}) * 10^5$$

A. Weakest buses identification

Table 5 ranks the top 15 weakest buses and lines for the equivalent Algerian electric power system 114-bus. The chosen buses which will receive the compensations devices are listed in Table 6.

Table 5. Stability index results for the Algerian 114-bus system.

Rank	Most Critical Nodes			Most Critical Lines					
	Bus Number	Q _{MaxFVSI} (Pu)	Q _{MaxLMN} (Pu)	Q _{MaxLPQ} (Pu)	Lines Number	Lines From-to	FVSI	LMN	LPQ
1	67	0.2691	0.2591	0.2791	27	17--27	0.9999	0.9999	0.9999
2	43	0.36076	0.37076	0.37076	10	15--16	0.9999	0.9999	0.9998
3	66	0.38422	0.36422	0.36422	72	24--25	0.9997	0.9999	0.9998
4	93	0.41	0.42	0.46	43	42--48	0.9995	0.9999	0.9998
5	77	0.41346	0.44346	0.41346	33	21--60	0.9995	0.9998	0.9998
6	41	0.47024	0.48024	0.50024	25	17--21	0.9995	0.9997	0.9998
7	50	0.48564	0.48564	0.52564	146	92--93	0.9999	0.9995	0.9995
8	55	0.49038	0.50038	0.52038	61	35--29	0.9995	0.9994	0.9995
9	51	0.49782	0.51782	0.50782	28	17--31	0.9995	0.9994	0.9993
10	89	0.51294	0.51294	0.51294	112	49--41	0.9993	0.9994	0.9991
11	56	0.5164	0.5164	0.5264	26	17--72	0.9998	0.9994	0.9991
12	69	0.5182	0.5182	0.5182	117	85--87	0.9992	0.9991	0.9998
13	68	0.5291	0.5491	0.5991	142	99--102	0.9995	0.9991	0.9991
14	12	0.5373	0.5173	0.5373	153	110--112	0.9990	0.9990	0.9996
15	54	0.5582	0.5682	0.5682	14	8--4	0.9990	0.9990	0.9993

Table 6. Compensation devices location.

Algerian 114-bus 41 ; 43 ; 50 ; 66 ; 67 ; 77 ; 93

B. Algerian Electric Power System 114-Bus simulation results

In this section the comparison of proposed algorithm runs on the equivalent Algerian electric power system (220/60 kV). The system consists of 175 transmission lines, 15 generator-buses, 99 load-bus, and 17 tap changer transformers. The switchable capacitor bank will be installed at bus bars 66 and 67, the total system real and reactive power demands are 3146.2 MW and 1799.4 Mvar. The Algerian power system data are given in Appendix B (Tables B.1 to B.3). The control variable limits and the description of the test systems are listed respectively in Tables 7 and 8.

Table 7. Setting of control variables.

Algerian 114- bus		
Var	Min	Max
T(P.u)	0.9	1.1
V_G (P.u)	0.9	1.1
Q_c (P.u)	0	0.5

Table8: Description of test systems.

Variables	Algerian 114 -bus
P_g (MW)	3146.2
Q_g (Mvar)	1799.4
P_{loss} (MW)	67.4567
Q_{loss} (MVAR)	265.840

Table 9 lists the optimal setting of control variables for this case for proposed PSO-GSA algorithm. From this table it can be seen that all control variables obtained by the proposed method are within the secure limits. In the other hand, the installation of reactive power is considered only for the most critical case (case 2, 3-2, 4 and 5) where the weakest buses become instable and need the reactive power to become stable.

The obtained load voltage profile of the Algerian 114- bus test system for all case studies obtained by proposed algorithm is shown in Figures 3. From the figure we can see all loads voltage magnitudes are within their minimum and maximum limits of 1.1 and 0.9.

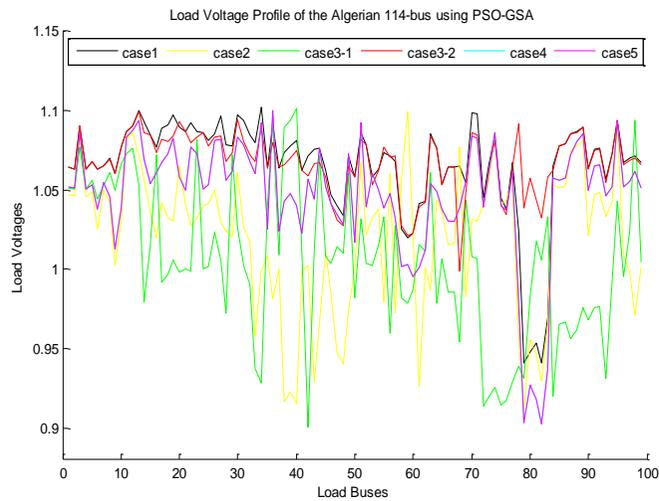


Figure 3. Load Voltage Profile of the Algerian 114-bus test system using PSO-GSA.

Table 9. Optimal Setting of Control Variables for the Algerian 114-bus using hybrid PSO-GSA.

Algerian -114bus (PSO-GSA)						
Variables	Case1	Case2	Case3-1	Case3-2	Case4	Case5
V ₄	1,1000	1,0976	1,0882	1,0971	1,0996	1,1000
V ₅	1,0944	1,0866	1,0806	1,0858	1,0892	1,0896
V ₁₁	1,0776	1,0537	1,0731	1,0512	1,1000	1,0510
V ₁₅	1,1000	1,1000	1,0862	1,1000	1,0855	1,1000
V ₁₇	1,1000	1,0679	1,0158	1,0432	1,0123	1,0744
V ₁₉	1,0994	1,0327	1,0085	1,0308	1,0428	1,0850
V ₅₂	1,1000	1,0653	1,0356	1,0755	1,0386	1,0873
V ₂₂	1,1000	1,0592	1,0134	1,0728	1,0445	1,0806
V ₈₀	1,0667	1,0594	0,9085	1,0602	1,0804	1,0621
V ₈₃	1,0923	1,0960	0,9284	1,0995	1,0800	1,0995
V ₉₈	1,0946	1,0831	0,9643	1,0755	0,0000	1,0846
V ₁₀₀	1,1000	1,1000	0,9552	1,1000	1,1000	1,1000
V ₁₀₁	1,0998	1,0958	0,9974	1,0943	1,1000	1,0988
V ₁₀₉	1,1000	1,1000	1,0491	1,1000	1,1000	1,1000
V ₁₁₁	1,0783	0,9812	1,1000	1,0978	1,0772	1,0700
T ₈₀₋₈₈	0,9337	0,9927	0,9000	1,0654	0,9000	0,9614
T ₈₁₋₉₀	1,1000	1,0566	0,9141	0,9712	1,0272	1,1000
T ₈₆₋₉₃	1,0487	1,0969	0,9000	1,0104	0,9795	1,1000
T ₄₂₋₄₁	0,9417	0,9887	1,1000	0,9274	0,9696	0,9105
T ₅₈₋₅₇	0,9654	0,9993	0,9018	0,9918	1,0495	0,9217
T ₄₄₋₄₃	0,9512	1,0310	0,9000	0,9557	0,9807	0,9440
T ₆₀₋₅₉	0,9814	0,9337	0,9573	0,9120	0,9800	0,9311
T ₆₄₋₆₃	0,9700	1,0830	0,9010	1,0332	1,0888	0,9789
T ₇₂₋₇₁	0,9693	1,0383	0,9001	0,9968	1,0087	0,9699
T ₁₇₋₁₈	0,9746	0,9656	0,9000	0,9037	0,9775	0,9463
T ₂₁₋₂₀	0,9851	0,9540	1,1000	0,9439	1,0341	0,9912
T ₂₇₋₂₆	0,9392	1,0187	0,9047	0,9284	1,0096	0,9028
T ₂₈₋₂₆	0,9989	1,0195	0,9902	1,0953	1,0783	0,9608
T ₃₁₋₃₀	0,9887	0,9980	0,9031	0,9565	1,0173	0,9672
T ₄₈₋₄₇	0,9772	1,0938	0,9000	0,9000	0,9919	0,9837
T ₇₄₋₇₆	0,9846	0,9269	1,0138	1,0765	1,0989	0,9740
Q _{c41}	0,0000	0,1714	0,0000	0,4714	0,4992	0,0160
Q _{c43}	0,0000	0,4841	0,0000	0,4781	0,3681	0,4954
Q _{c50}	0,0000	0,1031	0,0236	0,0631	0,0384	0,0180
Q _{c66}	0,0000	0,4852	0,0000	0,1160	0,4378	0,0536
Q _{c67}	0,0000	0,4984	0,0000	0,5000	0,3973	0,0658
Q _{c77}	0,0000	0,0675	0,0003	0,0419	0,1326	0,0133
Q _{c93}	0,0000	0,4999	0,4936	0,4985	0,0221	0,2362

Tables 10, 11 and 12 present the results obtained for different cases of study by using GSA, PSO, and PSO-GSA methods respectively. In comparing the results, we can notice that the minimum active power losses in cases 2 to 5 obtained by the proposed method are considerably reduced with regard to the other methods. For example, for Case 1, the proposed method allows to reduce the active power losses P_{loss} from 0.6745p.u to 0,5905p.u. And by using PSO and GSA the active power losses are reduced respectively to 0,5929p.u and 0,6000p.u. Also, for cases 2 to 5 we get further reduction of active power losses (P_{loss}) when using the hybrid PSO-GSA method. From these results we can see that the minimum found by the proposed method is better than the PSO and GSA method when used separately. This comparison proves the superiority of the proposed method.

Furthermore, from the result presented in tables 10 to 12, it can be noted that at the cases 1 (the base case) real power saving (P^{save}) and the annual cost saving (Wc^{save}) found by the hybrid PSO-GSA method are reduced by 1,60880; 11,5310; 11,6960% and 0,40643; 3,00968; 3,00950 % respectively compared to the two comparison methods (PSO and GSA). On the other hand the minimum P_{loss} , P^{save} and Wc^{save} , found for Cases 5, which is the most critical cases, compared to the PSO and GSA are respectively reduced by 1,70743; 14,8309; 14,8305% and 5,59457; 48,5297; 48,5298% .

This result shows that the reduction of the P_{loss} , P^{save} and Wc^{save} found by applying the proposed method compared to the other comparison methods (PSO and GSA) in the most critical case (Case 5) is significantly higher than that found in the base case (cases 1). This result shows the interest of hybridization between the PSO and GSA methods for solving complex optimization problems.

Table 10. Performance results of the GSA applied to the Algerian-114 bus.

Algerian -114bus (GSA)						
	Case1	Case2	Case 3-1	Case3-2	Case4	Case5
P_{loss}	0,5929	2,3332	0,3059	1,2049	1,6798	1,7440
P^Csave %	11,7303	7,1212	8,9347	4,0713	18,5291	5,3230
W^Csave (\$)	4141575,3960	9402720,8080	4265105,5680		20080094,1300	5153655,2450

Table 11. Performance results of the PSO applied to the Algerian-114 bus.

Algerian -114bus (PSO)						
	Case1	Case2	Case3-1	Case3-2	Case4	Case5
P_{loss}	0,6000	2,3235	0,3163	1,1952	1,6598	1,6798
P^Csave %	10,6997	7,5106	5,8377	4,8489	19,4991	8,8081
W^Csave (\$)	3770654,40	9916799,19	4231723,05		21131294,13	8527931,74

Table 12. Performance results of the proposed method applied to the Algerian-114 bus.

Algerian -114bus (PSO-GSA)						
	Case1	Case2	Case3-1	Case3-2	Case4	Case5
P_{loss}	0,5905	2,3054	0,2907	1,1922	1,6298	1,6516
P^Csave %	12,0943	8,2295	13,4587	5,0877	20,9541	10,3419
W^Csave (\$)	4270083,79	10866103,17	5734766,67		22708094,13	10012901,72

Appendix B: The Algerian electric power system 114-bus.

Table B.1. Bus DATA.

Bus	Type	Pd (MW)	Qd (Mvar)	Bus	Type	Pd (MW)	Qd (Mvar)	Bus	Type	Pd (MW)	Qd (Mvar)
1	1	0	0	39	1	20	10	77	1	7	3
2	1	36	17	40	1	21	10	78	1	13	7
3	1	64	31	41	1	53	32	79	1	14	7
4	3	210	150	42	1	0	0	80	2	157	107
5	2	335	250	43	1	31	18	81	1	0	0
6	1	78	37	44	1	0	0	82	1	75	36
7	1	55	26	45	1	12	6	83	2	70	51
8	1	50	24	46	1	0	0	84	1	46	34
9	1	40	19	47	1	21	10	85	1	45	22
10	1	42	21	48	1	0	0	86	1	0	0
11	2	96	47	49	1	13	6	87	1	32	15
12	1	31	15	50	1	4	2	88	1	46	22
13	1	13	6	51	1	1	1	89	1	34	17
14	1	136	65	52	2	56	27	90	1	18	9
15	2	0	0	53	1	16	8	91	1	44	21
16	1	0	0	54	1	21	10	92	1	10	5
17	2	0	0	55	1	18	9	93	1	0	0
18	1	0	0	56	1	33	20	94	1	48	23
19	2	11	5	57	1	35	21	95	1	35	17
20	1	14	9	58	1	0	0	96	1	0	0
21	1	70	52	59	1	36	17	97	1	42	20
22	2	42	25	60	1	0	0	98	2	13	6
23	1	23	11	61	1	27	13	99	1	105	50
24	1	60	36	62	1	22	11	100	2	33	16
25	1	17	8	63	1	49	29	101	2	50	24
26	1	55	26	64	1	0	0	102	1	34	16
27	1	0	0	65	1	11	5	103	1	66	32
28	1	0	0	66	1	35	21	104	1	18	9
29	1	37	18	67	1	10	5	105	1	0	0
30	1	30	15	68	1	11	5	106	1	64	31
31	1	0	0	69	1	20	10	107	1	65	37
32	1	40	24	70	1	7	3	108	1	22	11
33	1	29	14	71	1	36	22	109	2	37	18
34	1	29	14	72	1	0	0	110	1	13	6
35	1	33	16	73	1	36	22	111	2	94	56
36	1	17	8	74	1	0	0	112	1	24	12
37	1	11	5	75	1	0	0	113	1	23	11
38	1	20	10	76	1	12	6	114	1	24	12

1: P-Q bus 2: P-V bus 3: V- θ bus.

Table B.2. Generator DATA.

Bus	Pg (MW)	Qg (MVar)		Qmax (MVar)	Qmin (MVar)	Vg (pu)	Pmax (MW)	Pmin (MW)
4	750	0		400	-20	1.07	1200	0
5	450	0		200	-20	1.05	650	0
11	100	0		100	-50	1.05	150	0
15	100	0		100	0	1.04	150	0
17	450	0		400	0	1.08	600	0
19	115	0		60	0	1.03	150	0
52	115	0		50	0	1.04	150	0
22	115	0		50	0	1.05	150	0
80	115	0		60	0	1.08	150	0
83	100	0		200	-50	1.05	150	0
98	100	0		50	0	1.05	150	0
100	200	0		270	0	1.08	250	0
101	200	0		200	-50	1.08	250	0
109	100	0		100	-50	1.05	150	0
111	100	0		155	-50	1.02	150	0

Table B 3. Branch DATA.

Fbus	Tbus	R	V	B	Rate	Fbus	Tbus	R	X	B	Rate
2	1	0.0085	0.0403	0.0303	250	107	101	0.0334	0.1577	0.1189	250
6	1	0.0122	0.0578	0.0436	250	64	97	0.0178	0.0654	0.0470	200
2	6	0.0140	0.0498	0.0355	200	72	96	0.0152	0.0540	0.0386	200
4	42	0.0274	0.1295	0.0976	250	96	98	0.0203	0.0720	0.0515	200
4	42	0.0139	0.0122	0.1474	450	96	95	0.0015	0.0070	0.0053	200
4	3	0.0033	0.0158	0.0482	500	18	22	0.0290	0.1397	0.0017	80
5	3	0.0028	0.0189	0.0294	450	18	37	0.0256	0.1233	0.0015	80
5	4	0.0018	0.0126	0.0197	450	37	22	0.0171	0.0822	0.0010	80
4	7	0.0144	0.0678	0.0512	250	19	26	0.0058	0.0077	0.0017	60
15	16	0.0038	0.0135	0.0097	200	19	26	0.0058	0.0077	0.0017	60
16	3	0.0041	0.0144	0.0103	200	19	34	0.0019	0.0126	0.0001	80
16	14	0.0013	0.0045	0.0032	200	20	18	0.1348	0.2944	0.0013	50
8	42	0.0171	0.0629	0.0454	200	20	24	0.0376	0.1390	0.0006	40
8	4	0.0184	0.0870	0.0657	250	20	24	0.0368	0.1361	0.0006	40
10	7	0.0150	0.0709	0.0535	250	20	29	0.0319	0.1178	0.0005	40
10	11	0.0228	0.1076	0.0811	250	20	35	0.0428	0.1528	0.0006	40
7	6	0.0157	0.0740	0.0558	250	35	29	0.0458	0.1639	0.0007	40
11	42	0.0170	0.0806	0.0608	250	20	32	0.0708	0.2365	0.0010	60
6	3	0.0288	0.1012	0.0730	200	22	32	0.0342	0.1142	0.0005	60
9	2	0.0042	0.0284	0.0442	450	22	24	0.0239	0.0799	0.0003	60
9	3	0.0088	0.0600	0.0933	450	22	24	0.0239	0.0799	0.0003	60
13	12	0.0501	0.2365	0.1784	250	23	30	0.0239	0.0799	0.0003	60
10	13	0.0464	0.2190	0.1652	250	23	36	0.0136	0.0457	0.0002	60
17	21	0.0065	0.0244	0.0176	200	36	30	0.0273	0.0913	0.0004	60
17	21	0.0073	0.0278	0.0202	200	33	18	0.0205	0.0685	0.0003	60
17	72	0.0197	0.0732	0.0530	200	32	33	0.0239	0.0799	0.0003	60
17	27	0.0046	0.0237	0.1003	300	26	25	0.0139	0.0517	0.0002	30
17	31	0.0061	0.0311	0.0617	350	24	25	0.0164	0.0608	0.0003	60
31	28	0.0017	0.0088	0.0746	300	26	34	0.0049	0.0318	0.0002	60
17	64	0.0198	0.0727	0.0525	200	29	26	0.0119	0.0158	0.0034	60
21	44	0.0240	0.0861	0.0615	200	29	39	0.0126	0.0820	0.0004	80
60	31	0.0037	0.0253	0.0393	450	38	34	0.0047	0.0307	0.0002	80
21	60	0.0056	0.0263	0.0198	250	18	73	0.1557	0.3427	0.0015	50
60	44	0.0122	0.0578	0.0436	250	18	73	0.0854	0.3028	0.0012	60
58	44	0.0121	0.0569	0.0429	250	62	18	0.0508	0.1941	0.0008	60
72	101	0.0213	0.1007	0.0760	250	20	52	0.0873	0.2162	0.0011	50
72	58	0.0183	0.0863	0.0651	250	20	52	0.0875	0.2167	0.0011	50
58	75	0.0148	0.0701	0.0528	250	54	59	0.1188	0.3063	0.0015	50
75	107	0.0185	0.0876	0.0660	250	52	59	0.0360	0.1014	0.0005	50
75	74	0.0006	0.0026	0.0026	250	57	51	0.1227	0.4098	0.0018	60
44	42	0.0248	0.0903	0.0649	200	57	77	0.1366	0.4566	0.0020	60
44	42	0.0183	0.0864	0.0651	250	52	53	0.0937	0.1788	0.0007	35
42	48	0.0074	0.0506	0.0786	450	53	54	0.0937	0.1788	0.0007	35
48	44	0.0025	0.0158	0.0245	450	52	30	0.0722	0.1789	0.0009	50

Fbus	Tbus	R	X	B	Rate	Fbus	Tbus	R	X	B	Rate
71	70	0.1599	0.3148	0.0013	35	98	97	0.0121	0.0448	0.0325	200
40	41	0.0586	0.1623	0.0008	50	99	100	0.0231	0.1089	0.0821	250
40	50	0.1343	0.3645	0.0016	35	87	100	0.0102	0.0694	0.0105	450
71	69	0.1093	0.3653	0.0016	60	100	84	0.0065	0.0442	0.0687	450
70	68	0.1204	0.2180	0.0009	35	84	80	0.0074	0.0506	0.0786	450
43	46	0.1025	0.3425	0.0015	60	86	81	0.0055	0.0379	0.0589	450
51	43	0.2067	0.3556	0.0015	35	98	99	0.0163	0.0580	0.0414	200
54	55	0.1196	0.3996	0.0018	60	101	102	0.0116	0.0547	0.0413	250
55	43	0.1708	0.5708	0.0025	60	99	102	0.0116	0.0547	0.0413	250
73	62	0.0410	0.1370	0.0006	60	99	101	0.0111	0.0759	0.1179	450
73	67	0.3347	0.7007	0.0031	40	98	94	0.0357	0.1275	0.0918	200
68	67	0.1648	0.3569	0.0015	40	94	82	0.0056	0.0263	0.0198	250
29	26	0.0119	0.0158	0.0034	60	92	93	0.1624	0.4088	0.0099	60
73	66	0.1623	0.5752	0.0023	60	93	91	0.0304	0.1074	0.0021	60
63	66	0.0683	0.2283	0.0010	60	93	91	0.0379	0.1342	0.0027	60
63	65	0.0557	0.1861	0.0008	60	90	89	0.0776	0.2400	0.0052	60
63	65	0.0557	0.1861	0.0008	60	88	89	0.1354	0.4100	0.0089	60
56	54	0.1025	0.3425	0.0015	60	90	93	0.1852	0.3189	0.0068	60
57	56	0.1196	0.3996	0.0018	60	103	110	0.0185	0.0876	0.0660	250
57	56	0.1196	0.3996	0.0018	60	110	112	0.0185	0.0876	0.0660	250
47	50	0.1196	0.3996	0.0018	60	103	114	0.0419	0.1979	0.1493	250
47	46	0.0342	0.1142	0.0005	60	109	108	0.0148	0.0701	0.0528	250
67	66	0.1128	0.2794	0.0014	50	109	107	0.0388	0.1833	0.1382	250
49	41	0.1265	0.4225	0.0019	50	112	114	0.0190	0.0896	0.0675	250
19	78	0.0042	0.0055	0.0012	60	112	111	0.0297	0.1402	0.1057	250
19	79	0.0105	0.0139	0.0030	60	113	111	0.0167	0.0787	0.0608	250
59	61	0.0513	0.1816	0.0007	60	80	88	0.0123	0.3140	0.0000	400
45	46	0.0171	0.0605	0.0002	60	81	90	0.0062	0.1452	0.0000	240
85	87	0.0158	0.0745	0.0562	250	86	93	0.0012	0.0742	0.0000	240
85	86	0.0139	0.0657	0.0495	250	42	41	0.0012	0.0742	0.0000	240
85	81	0.0099	0.0467	0.0352	250	58	57	0.0012	0.0742	0.0000	240
87	106	0.0105	0.0495	0.0373	250	44	43	0.0029	0.1053	0.0000	120
87	82	0.0056	0.0266	0.0200	250	60	59	0.0014	0.0516	0.0000	360
87	99	0.0322	0.1249	0.0909	200	64	63	0.0019	0.0700	0.0000	180
103	105	0.0130	0.0613	0.0462	250	72	71	0.0012	0.0742	0.0000	240
105	101	0.0171	0.0806	0.0608	250	17	18	0.0014	0.0516	0.0000	360
105	104	0.0015	0.0070	0.0053	250	21	20	0.0016	0.0525	0.0000	240
103	106	0.0208	0.0983	0.0741	250	27	26	0.0024	0.1484	0.0000	120
81	82	0.0303	0.1075	0.0768	200	28	26	0.0024	0.1484	0.0000	120
80	82	0.0319	0.1129	0.0807	200	31	30	0.0007	0.0495	0.0000	360
80	84	0.0191	0.0676	0.0483	200	48	47	0.0012	0.0742	0.0000	240
84	83	0.0051	0.0180	0.0129	200	74	76	0.0089	0.3340	0.0000	40
82	83	0.0191	0.0676	0.0483	200						
100	98	0.0102	0.0598	0.0754	250						
100	97	0.0111	0.0759	0.1179	450						

7. Conclusion

The Hybrid Particle Swarm Optimization and Gravitational Search have been used for solving the reactive power planning using SVC's device. Various critical situations are simulated to prove the effectiveness of the proposed algorithm and to ensure viability of the power system in contingency scenarios. The locations of the SVC's devices considering voltage security are determined using three different stability indexes namely, Fast Voltage Stability Index (FVSI), Line stability index (Lmn) and Line Stability Factor (LPQ).

The simulation results show the high performance of PSOSGA algorithm on minimizing the transmission power losses and on improving the real power and annual cost savings. The analyses of the results are very promising since the main objectives of the proposed technique were achieved:

- State and control variables were brought to their range limits.
- Voltage stability is ensured in the most critical bus in the system by installing the compensation devices.
- Minimum of SVC's devices amount.
- Minimum of transmission active power losses.
- The best real power saving and the annual cost saving.

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List of symbols

- f_{VAR} : The objective function of the compensation devices investment cost;
 f_{wc} : The objective function of the cost of energy losses ;
 G and H : Equality and inequality constraints of the system;
 U : The vector of controls variables and X is the vector of state variables;
 C_{fi} : The fixed installation cost of the reactive power sources at the i^{th} bus (1771.59 (\$));
 C_{ci} : The cost per MVAR of the compensation devices at the i^{th} bus (5314.8 (\$/MVAR));
 Q_{ci} : The reactive power compensation at the i^{th} bus (MVAR) ;
 N_{VAR} : The number of installed compensation devices;
 f_{Ploss} : The objective function of real power losses problem;
 V_i, V_j : The voltage magnitudes;
 G_k : The conductance of branch k ;
 θ_i, θ_j : The voltage angel at buses i and j ;
 N_{Li} : The number of transmission lines; h is the energy cost (0.06 (\$/kWh));
 P_{Di}, Q_{Di} : Real and reactive power at bus i ;
 P_{Gi}, Q_{Gi} : Real and reactive powers of the i^{th} generator;
 V_i : The voltage magnitude at bus i ;
 N_{Bus} : The number of buses;
 G_{ij}, B_{ij} : The conductance and susceptance between i and j ;
 θ_{ij} : The phase angle difference between the voltages at i and j ;
 θ_{ji} : The phase angle difference between the voltages at j and i ;
 N_{bus} : The number buses;
 N_G : The number of generators;
 N_c : The number of switchable VAR sources;
 N_T : The number of transformers;
 N_{load} : The number of load buses and N_{Li} the number of transmission lines;
 Z : The line impedance;
 X : The line reactance;
 Q_j : The reactive power flow at the receiving end ;
 V_i : The sending end voltage;
 X : The line reactance;
 Q_r : The reactive power at the receiving end;
 V_i : The sending end voltage;
 Θ : The line impedance angle;

δ : The angle difference between the supply voltage and the receiving voltage;
 t : The current epoch ;
 $V_i(t)$: The velocity of agent i at iteration t ;
 c_j' : A weighting factor;
 w : The weighting function;
 $rand$: A random number between interval $[0, 1]$;
 $ac_i(t)$: The acceleration of agent i at iteration t ;
 $gbest$: The best solution;
 M_{aj} : The active gravitational mass related to agent j ;
 M_{pi} : The passive gravitational mass related to agent i ;
 $G(t)$: The gravitational constant at time t ;
 ε : A small constant;
 $R_{ij}(t)$: The Euclidian distance between two agents i and j ;
 α , G_0 : Descending coefficient and initial value respectively;
 $iter$: The current iteration;
 $maxiter$: The maximum number of iterations ;
 $rand_j$: A random number in the interval $[0, 1]$;
 t : A specific time ;
 M_{ii} : The mass of object;
 σ_{v_i} : The penalty factors for the bus voltage limit violation;
 $\sigma_{Q_{Gi}}$: The penalty factors for the generator reactive power limit violation;
 $\sigma_{S_i^t}$: The penalty factors for line flow violation;



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