ABC-Based Optimization of Cluster Head Selection in Wireless Sensor Networks

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Abstract: There are several advantages of using Wireless Sensor Networks (WSNs) compared to wired sensor networks, such as lower cost, easier deployment, and better scalability. WSNs are employed in many fields such as medicine, industry, and economics, among others. As the use of WSNs grows in a number of applications, further work is being done on research and development of new methods to enhance their performance. Selecting the proper routing protocol is a significant consideration and an important task for all WSN applications. Many pieces of research focused on the routing problem which can contribute to the improvement of WSN lifetime and problem-solving techniques. This paper, however, discusses the various existing optimization techniques, including numerous modifications to the LEACH protocol. It then conducts a series of simulations to notice the difference between utilizing LEACH alone and LEACH with the ABC optimization algorithm. The purpose of these experiments is to prove the improvement made by the ABC on the residual energy which is reflected positively in the number of received packets and minimize the dead nodes. This will demonstrate how to optimize WSN system towards energy conservation. LEACH with ABC revealed much better results than LEACH on its own. This indicates one possible optimization technique that limits dead nodes and increases overall residual energy usage and the network lifetime. Many scenarios are simulated to validate the improvement of the WSN performances.

Keywords: WSN; LEACH; ABC; optimization

1. Introduction

Wireless Sensor Network (WSN) consists of a group of sensors (called nodes), deployed over a specific area for data collection and monitoring of physical phenomena. Collected data are transferred by wireless communication and classified in a central node called the Base Station (BS). WSNs are used for physical condition evaluation such as pollution, temperature, noise, flooding, and wind speed. WSN may be a group of hundreds or thousands of nodes connected in certain topologies depending on the type of measured physical phenomena and supervised area [1]. WSNs were originally developed for military applications such as detecting enemy forces and monitoring demilitarized zones as strategic war tools [2]. Industrial applications of WSN are unlimited since each day a new application appears in the market, especially with the era of the Internet of Things [3-4]. WSNs are used in medical applications as a subsystem for enhancing disease detection as well as monitoring the health status of patients inside and outside hospitals [5]. WSNs are also present in many agriculture and environment applications such as measuring water level, soil moisture in the field, flooding, and weather prediction [6]. WSN communicates over a wireless channel with the capability of performing a simple processing operations on the collected data and transmitting them from node-to-node to the BS. Due to their low-price and low-complexity, sensors are characterized by their short transmission range, poor processing competence, low data rates, low on-chip memory, and limited available supply. Since WSNs are self-contained systems, energy management is essential for devices. The energy stored in batteries inside sensors is consumed by the information transmission from node to node. Wireless transmission requires a certain level of energy to perform data circulation correctly depending on the distance between nodes and the amount of data exchanged. Routing data across WSN is

Received: April 5th, 2020. Accepted: May 26th, 2021 DOI: 10.15676/ijeei.2020.13.2.3 then the principal source of energy consumption. Routing is one of the critical tasks in WSNs, and because of their fundamental characteristics, they are challenging to work with in any application[7]. Based on network architecture, routing protocols in the WSNs can be classified into two classes: flat routing and clustering routing. Due to various advantages, clustering routing has become an attractive class of routing strategy in WSNs [8]. Clustering is one of the techniques used to efficiently manage node energy. In this structure, a single-layer network is used to decrease power consumption by holding the sensor efficiently to engage it in a two-hop connection within groups. Cluster routing mechanisms are more accurate and preferable for WSN with continuous data flow [9]. The Low-Energy Adaptive Clustering Hierarchy (LEACH) protocol is a TDMA-based protocol integrated with clustering and a simple routing protocol in WSNs. LEACH is a protocol that combines the notion of energy efficiency cluster-based routing together with data aggregation to achieve scalable routing and fair media access with improved performance in system lifetime [10]. Artificial Bee Colony (ABC) is one of the most promising optimization techniques in this field. It is founded on the biological process natural conduct of real honey bees in food foraging. Moreover, ABC algorithm has a lot of advantages such as simplicity, flexibility and robustness [11]. The aim of this research is to conduct a comparative study on the performances of LEACH and ABC protocols focusing on the problem of optimal selection of cluster head (CH) in WSNs.

The article is organized as follows: the state of art is reviewed in Section 2; the theoritical information about LEACH and ABC are presented in Section 3; To illustrate the improved performance of the application of ABC for CH selection, the simulation of two case studies is given in Section 4; Section 5 concludes the article.

2. Literature Survey

The present research has three components: the WSN routing protocols, LEACH protocols, and the application of ABC to optimally resolve the problem of CH selection. A limited survey is conducted according to the three overlapping components taking into account the importance and the recentness of published research. A dynamic selection of CH is presented in [12], where cluster nodes select the next CHs depending on that residual energy of all cluster nodes. An energy-efficient protocol for heterogeneous WSN based on clustering technique is proposed by [13]. To increase the WSN lifetime, the protocol uses channel state as a function for CHs selection. Simulation proved the effectiveness of the proposed algorithm in stability compared to a classical protocol such as LEACH, and SEP. The relationship between sensor-node energy and the method of choosing the best CH candidate through the suggestion of a novel protocol has been investigated in [14]. The proposed method creates a dynamic cluster employing secure sensor protocols for information via negotiation where its drawbacks are controlled. Many routing algorithms, and data transmission protocols have been proposed for WSNs where energy sensibility is the major design issue. Many kinds of clustering protocols have been designed to balance and optimize the sensor node lifetime. LEACH protocol based on clustering protocol with randomized rotation of CHs has been proposed in [15]. It uses localized coordination and is able to construct scalable, robust, and dynamic networks. A novel protocol for data routing in WSN named the Energy Efficient LEACH (EE-LEACH) has been introduced in [16]. The proposed protocol offers an energy-efficient routing strategy for WSN based on efficient data gathering and optimum clustering. The importance of WSNs energy management is remarked in [17], where a novel protocol is proposed based on LEACH. A simulation of various parameters by MATLAB has been done to validate the good performances of the new protocol. Threshold equations are used for the energy evaluation of all sensors. A cluster-based scheme is proposed as a solution for the energy extension. An Extended High Energy First (EHEF) clustering protocol is proposed in [18] which is able to perform multi-hop transmissions. It is a Multi-Input Multi-Output (MIMO) scheme extending by 75% the stand-alive nodes in the network compared to the normal LEACH. A general survey of LEACH variants-based routing protocols is presented in [19] and the improvement of each research is outlined.

The ABC algorithm has been first proposed by Karaboga at Ercives University (Turkey) in 2005, which could simulate the behavior of honey bees in real life and is used as an optimization technique [20]. The colony of artificial bees is modeled by three groups of bees: employed bees, onlookers, and scouts where for every food source, the model considers only one employed bee. ABC is a novel, robust optimization technique that can be used to find the optimal solution for a variety of engineering problems. The use of ABC has been first explored in a significant review to solve the clustering analysis problem in [21]. The CHs election based on the Particle Swarm Optimization technique has been studied in [22]. The proposed method is showing improved performance compared with the LEACH method. A novel clustering routing protocol based on ABC to find the best CH candidate is proposed in [23]. This algorithm is an election process of the optimal CH and assistant CH by introducing assistant CH in the cluster and ABC. A clustering algorithm for an efficient cluster mechanism with improved CH selection based on a multi-objective ABC function is presented in [24]. An evaluation and comparison of the proposed algorithm against the existing well-known Swarm-intelligent-based techniques proves its superiority compared to others in terms of packet delivery ratio, average energy consumed, average throughput, and network life. A trust-based CH election protocol for multi-hop WSNs using ABC Algorithm is suggested in [25]. CHs usually consume their energy soon, so a mechanism for dynamic change of CHs is proven to be a positive step toward uniform energy utilization. An important survey about the new aspect of the analysis of routing in WSN that had never been considered in the previously available literature is presented in [26]. This work can be a guideline for future researchers to understand where we are today in the WSN technology, routing with optimized energy consumption, and the factors that have a direct impact on the energy in WSN.

3. Theoretical Backgrounds

A. LEACH Protocol

LEACH stands from Low-Energy Adaptive Clustering Hierarchy and is first introduced by W. Heinzelman et al. in 2000 [27]. LEACH is a cluster-based routing algorithm with the capability of auto adaptation and auto organization. The major goal of LEACH is to improve WSN lifetime. CHs are chosen in an ordered way after separating WSN into many clusters. This process presents the central concept of the LEACH protocol. Given that the consumed energy for CH is greater than that for non-CH nodes, different nodes are selected as CH successively balancing the consumption of energy within all nodes [15]. Data are collected from cluster nodes by the CH and then passed to BS in one or more hops. LEACH is an iterative algorithm where each round is composed of two steps: setup and steady states as shown in Fig. 1 [8]. The algorithm starts by examining the power of the sensor node, as the node is considered dead if its energy falls below a predetermined threshold. If the number of live nodes reaches a minimum (according to the application), then WSN will be out of service.

Step stage: -

A distributed algorithm without the requirement of possible communication with the BS is used for cluster formation. This algorithm selects CH and distributes its location to all other nodes. At each round, nodes use a random probabilistic algorithm to determine whether they will become a CH. Three sub-stages constitute the setup stage. They are announcement, cluster formation, and transmission chart initiation. LEACH is built on the principle that a selected node as a CH should not get reselected every time. A sensor node defines a random value between 0 and 1 used to choose the CH. Th(n) represents the threshold value and is evaluated by (1) [15]:

$$Th(n) = \begin{cases} \frac{p}{1 - p(r \mod p^{-1})} & \text{if } n \in GN\\ 0 & \text{otherwise} \end{cases}$$
(1)



Figure 1. LEACH Protocol

where the CH probability is represented by (p) in the round number (r), and GN represents the set of nodes that have not been CH in the last 1/p rounds. If the selected random value by a specific node is less than Th(n), then this node will be selected as CH for the actual round. After selecting the CH, the information about the new CH is sent to all cluster nodes by a Carrier Sense Multiple Access message (CSMA). This small size message includes the node's ID and a header that specifies the type of message as an announcement message. All WSN nodes receive these announcements originated from different candidate CHs with different signal strengths. The allocation of a specific node to a specific cluster is made by a decision from the node itself regarding the power intensity of the received announcement. By a CSMA-MAC message, the previous allocation is transmitted back to the selected CH by sending a Join-Request message back to the CH as presented in the first part of Figure 1.

• Steady state stage: -

The second part of Fig. 1 shows that this stage can be subdivided into three sub-stage which are the transmission of data from a different location to CH, data aggregation and then data transmission to BS. A TDMA timetable is created by CH in each cluster, and a random

CSMA schedule is distributed to all cluster nodes. Each node uses its TDMA slot (schedule) for information routing to CH of its cluster. To improve the conservation of the nodes' energy, the protocol switches off all passive nodes of the cluster where only the active node and CH are still switching on. CH receives all data from various origin, aggregates data and possibly compress it, and transmits the fused data to BS. The most energy consumption happens in the present steady-state stage. Note that the value of T_r in Fig. 1 represents the round time in sec. Thus, this stage consumes larger time than the setup stage. The procedures included in both stages are repeated periodically from the CH selection to data received by the BS. The LEACH begins with the CH selection in the setup stage and finishes by transmitting collected information from various nodes to the BS in the steady-state stage.

B. ABC Protocol

Artificial Bee Colony (ABC) is an optimization algorithm introduced by Karaboga in 2005. It was inspired by the intelligent behavior of honeybees. ABC, by its simplicity, can be compared to Particle Swarm Optimization (PSO) and Differential Evolution (DE) algorithms. It utilizes only common control parameters like colony size and maximum cycle number. ABC provides a population-based investigation procedure in which individuals named foods positions are adjusted by the artificial bees (with time) and the bee's goal is to find out the places of food sources with high nectar as presented in Fig. 2 [11]. Three bee classes in the ABC are scouts, employed, and onlookers' bees. One bee symbolizes a position in the search space. Based on the bees' experience, artificial bees select their source of food and adapt their next positions. Scouts fly and select the food sources at random without utilizing learned experience. If the nectar quantity of a newly discovered source is greater than the previous one in their memory, bees save the new position and omit the previous. Thus, ABC integrates local search mode carried out by employed and onlooker bees, with global search modes, managed by onlookers and scouts, and tries to balance exploration and exploitation process. The application of ABC to the WSN routing for a network composed of n-CH sensors, gives a dimension of the bees fly in the search space equal to (n).



Figure 2. ABC Protocol

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CHs are located by bees and onlooker bees still waiting on "the dance area" to select the food source. Some sources of food with prior knowledge are visited by the second type of bee which is the employed bee. Finally, a scout is a bee that performs an arbitrary search for food sources. The optimal solution to the issue is represented by the placement of the new source of food. The fineness of the associate problem solution is the nectar quantity of the founded sources. In the ABC algorithm, food sources are allocated one-to-one to employed bee where the initial sources are arbitrary generated as starting sources. The best food source location is updated in (2) by inspecting the nearby food source by every employed bee in the network. Bee evaluates the quantity of the food where it moves toward the new one in the case of an improvement in the quantity otherwise it keeps working on the present source of food [20].

$$V_{ij} = X_{ij} + \theta_{ij} (X_{ij} - X_{kj})$$
(2)

Where θ is a random number between (-1,1), V_i , is a candidate solution, X_i is the current solution and X_k is a neighbor solution and $j \in \{1, 2, 3, ..., D\}$ is a randomly chosen index where D is the dimension of the solution vector. After accomplishing the search, employed bees broadcast the information concerning the location of the newly discovered food sources with onlookers. The nectar quantity of the discovered source is estimated by (3), and the information is used to select the source by a probability which is the function of the nectar quantity.

$$P_{i} = \frac{fit_{i}}{\sum_{n=1}^{SN} fit_{n}}$$
(3)

where the food source location is represented by (i), SN defines the employed number (equal to sources number), and fit_i represents the efficiency rate related to the nectar quantity of the solution (i). This selection is performed by the onlookers based on collected information by employed bees. New sources are selected which correspond to CH in our routing problem by the previous process as roulette wheel selection method. At the moment that food sources have been selected by onlookers one-to-one, followed by a new search of the new nearest source, and then evaluated the nectar quantity of the new source. Onlooker and employed bees can be converted to scout bees if their relative sources of food are consumed. Consumed sources are labeled as deserted and employed bees allocated to these sources are converted to be scout bees. A new possible solution calculated by the scout bee where deserted location is symbolized by X_i :

$$X_{i}^{J} = X_{\min}^{J} + rand(0,1)(X_{\max}^{J} - X_{\min}^{J})$$
(4)

4. Simulation Results

A 20-node network with 5 clusters is simulated using MATLAB. The initial energy is considered to be 0.1 Joules. The results of the 20-node WSN are presented in Fig. 3. The topology of the case study is randomly distributed by the program as presented in Fig. 3-a. Fig. 3-b shows a comparison of the residual energy using ABC and LEACH protocols for 1500 iterations (rounds). The two curves start from the same point (energy= 0.1 Joules), but after approximately (500) rounds, the residual energy in the case of LEACH protocol is disappeared while in the ABC the energy continuously exists which is better than LEACH protocol. At the end of the 1500 rounds, the ABC have 0.011275 J whereas in the case of LEACH only 0.000097 J remain (y-axis presents the energy, but values are multiplied by (100) time for clarity). The residual energy is directly reflected on the alive nodes as shown in Fig. 3-c where after 1500 rounds the alive nodes of ABC are (9) nodes while in the case of using LEACH protocol only one (1) node remains alive. The number of received packets depends on alive nodes as in Fig. 3-d, where in the case of ABC a number of 9030400 packets is received while for LEACH the number is limited to only 3131200 yielding an improvement of 288%. Previous results are confirmed by a 40-node WSN with five clusters where the simulation results are presented in Fig. 4. A comparison of the residual energy using ABC and LEACH protocols for this network is outlined for the same number of rounds (1500) in Fig. 4-a. The two curves start from the same point (energy= 0.2 Joules), but after (870) rounds the residual energy of the LEACH protocol already vanishes while in the ABC, it is equal to 0.074844 J (37% of the original energy). The ABC has maintained better performance than the LEACH protocol up till the end of round 1500 where the ABC stills keeping 0.01955 J (9.7% of the original energy). However, the residual energy is directly reflecting the alive nodes as in Fig. 4-b, where after 870 rounds the alive nodes of LEACH are zero whereas in the ABC all nodes still alive. At the end of the 1500 rounds, 4 nodes still alive, which proves again that the ABC shows better performance.









a)- Residual energy



(b)- Alive node Figure 4. 40-node WSN

5. Conclusion

This work is concerned with the improvement of routing protocol performance of the dynamic clustering routing protocols in WSN. A study is conducted on the evaluation of the performances of routing algorithm- based LEACH protocol. The routing algorithm is improved by using ABC optimization protocol as a tool for a dynamic CH selection. Residual energy collected from the simulation of LEACH alone and compared to LEACH with ABC for all scenarios shows a significant improvement in the case of ABC-based LEACH.

The simulation also proved the improvement made by the use of ABC on the dead node number, network lifetime, and received packets. Many scenarios were implemented to evaluate the improvement made by the ABC to the energy consumption. The results illustrate the superiority of the ABC-based LEACH compared to LEACH protocol alone. The improvement becomes more pronounced for networks with a high number of clusters.

6. References

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